



Automated Machine Learning on Graphs

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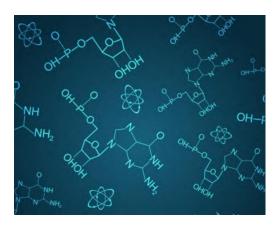
Graphs are Ubiquitous



Social Network



Traffic Network

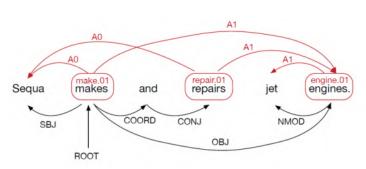


Biology Network



Information Network

Graph Applications



pager1

hard-2

poe-GIT

face-1

poe-GIT

face-1

poe-GIT

face-1

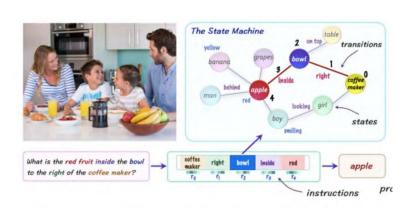
cup-2



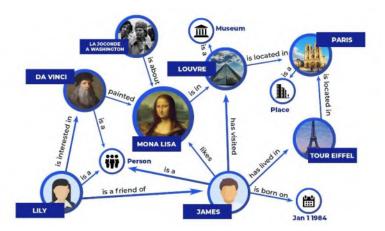
Natural Language Processing

Computer Vision

Data Mining

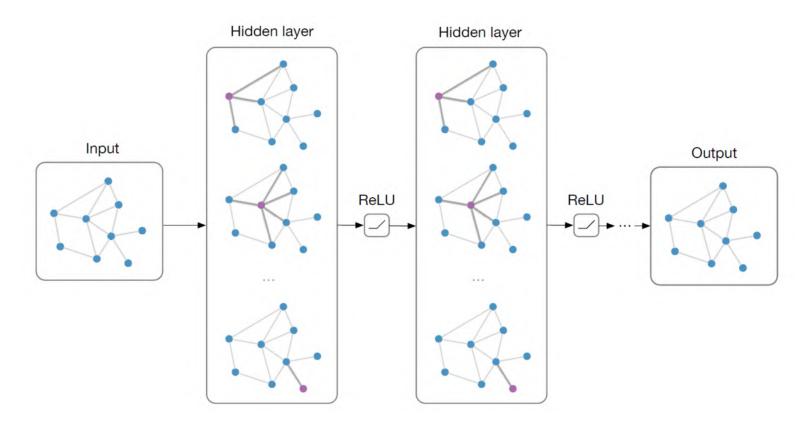


Multimedia



Information Retrieval

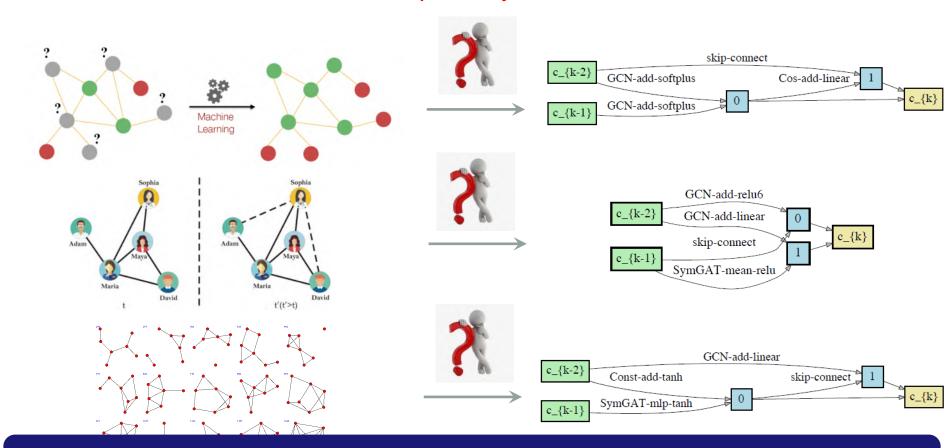
Graph Neural Network



- Design neural networks directly applicable for graphs for end-to-end learning
- Message-passing framework: nodes exchange messages along structures

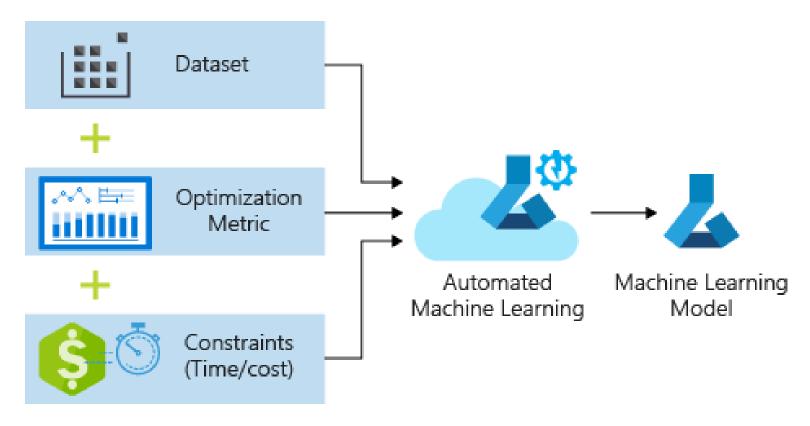
The Existing Problems in Traditional Graph Learning Methods

- Manually design architectures and hyper-parameters through trial-and-error
- Each dataset/task is handled separately



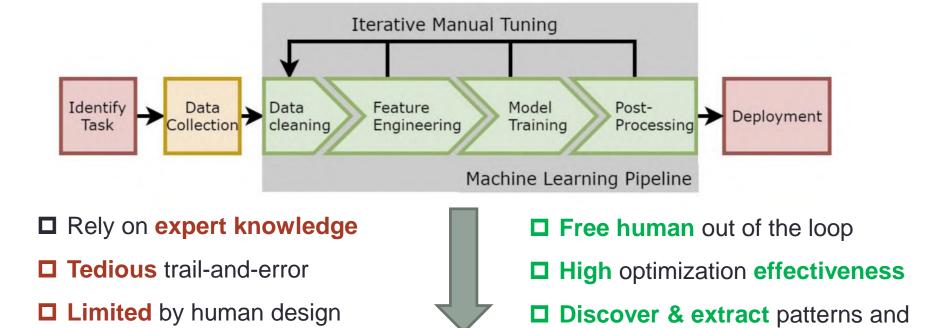
The adaptivity of graph machine learning is limited!

A Glance of AutoML



Design ML methods → Design AutoML methods

ML vs. AutoML

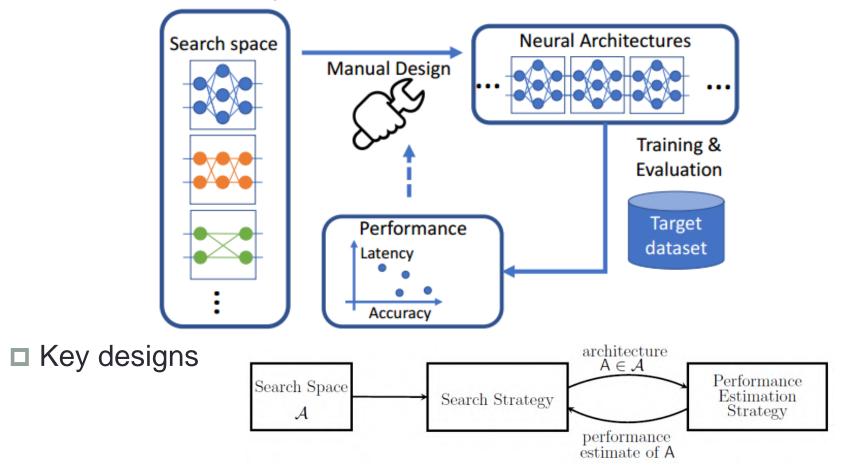


combinations automatically

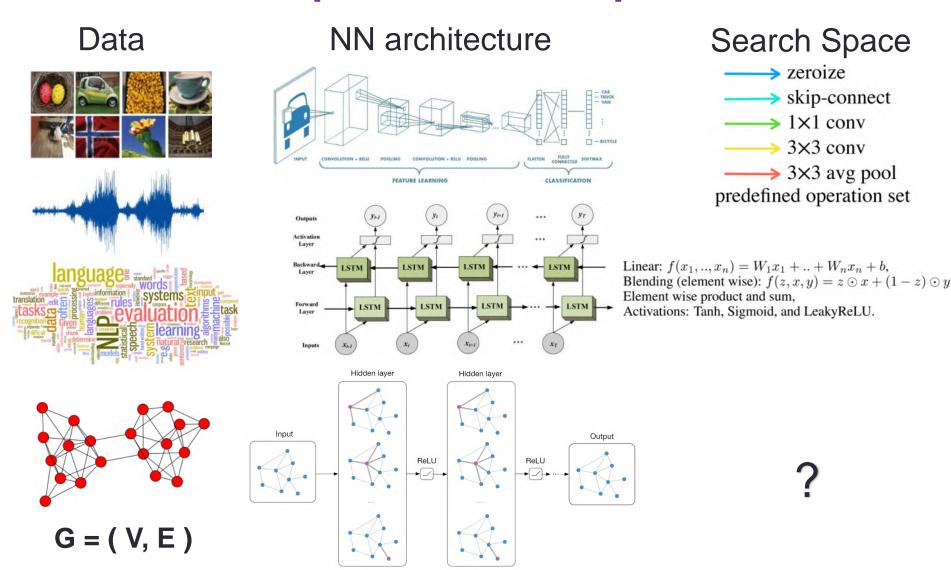


Graph Neural Architecture Search (NAS)

■ NAS: automatically learn the best neural architecture



Graph NAS: Search Space



Graph NAS Search Space

$$\begin{aligned} \mathbf{m}_i^{(l)} &= \overline{\mathbf{AGG}^{(l)}} \left(\left\{ a_{ij}^{(l)} \mathbf{W}^{(l)} \mathbf{h}_i^{(l)}, \forall j \in \mathcal{N}(i) \right\} \right) \\ \mathbf{h}_i^{(l+1)} &= \overline{\sigma} \left(\overline{\mathbf{COMBINE}^{(l)}} \left[\mathbf{m}_i^{(l)}, \mathbf{h}_i^{(l)} \right] \right), \end{aligned}$$

- \square AGG(·): how to aggregate information from neighbors
 - Requirement: permutation-invariant
 - □ Common choices: mean, max, sum, etc.
- \square a_{ij} : the importance of neighbors
- COMBINE(·): how to update representation
 - □ Common choices: CONCAT, SUM, MLP, etc.
- $\square \sigma(\cdot)$: Sigmoid, ReLU, tanh, etc.

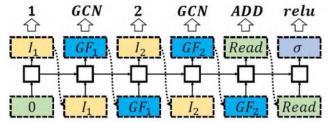
Type	Formulation
CONST	$a_{ij}^{\text{const}} = 1$
GCN	a ^{gcn} — 1
GAT	$a_{ij}^{\text{gat}} = \frac{1}{\sqrt{ \mathcal{N}(i) \mathcal{N}(j) }}$ $a_{ij}^{\text{gat}} = \text{LeakyReLU}\left(\text{ATT}\left(\mathbf{W}_{a}\left[\mathbf{h}_{i}, \mathbf{h}_{j}\right]\right)\right)$
SYM-GAT	$a_{ij}^{ ext{sym}} = a_{ij}^{ ext{gat}} + a_{ji}^{ ext{gat}}$
COS	$a_{ij}^{\cos} = \cos\left(\mathbf{W}_a \mathbf{h}_i, \mathbf{W}_a \mathbf{h}_j\right)$
LINEAR	$\begin{vmatrix} a_{ij}^{\text{lin}} = \tanh\left(\text{sum}\left(\mathbf{W}_a\mathbf{h}_i + \mathbf{W}_a\mathbf{h}_j\right)\right) \\ a_{ij}^{\text{gene}} = \tanh\left(\text{sum}\left(\mathbf{W}_a\mathbf{h}_i + \mathbf{W}_a\mathbf{h}_j\right)\right)\mathbf{W}_a' \end{vmatrix}$
GENE-LINEAR	$a_{ij}^{\text{gene}} = \tanh\left(\operatorname{sum}\left(\mathbf{W}_a\mathbf{h}_i + \mathbf{W}_a\mathbf{h}_j\right)\right)\mathbf{W}_a'$

 $lue{}$ Dimensionality of $h_i^{(l)}$, the number of attention heads (when using attention)

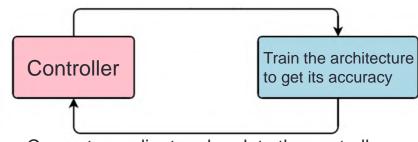
Graph NAS Search Strategy

- Most previous general NAS search strategies can be directly applied
 - Reinforcement learning

□ Controller:

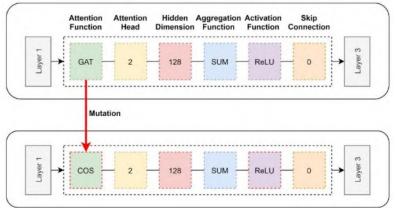


Sample architecture with probability

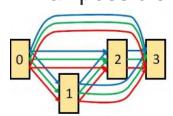


- Evolutionary
 - □ Define how to evolve and how to select

Compute gradient and update the controller



- Differentiable
 - □ Super-net: mix all possible operations



$$\mathbf{y} = o^{(x,y)}(\mathbf{x}) = \sum_{o \in \mathcal{O}} \frac{\exp(\mathbf{z}_o^{(x,y)})}{\sum_{o' \in \mathcal{O}} \exp(\mathbf{z}_{o'}^{(x,y)})} o(\mathbf{x})$$

$$\alpha = \alpha - \nabla_{\alpha} \mathcal{L}_{val}(\mathbf{W}(\alpha), \alpha)$$

$$\mathbf{W} = \mathbf{W} - \nabla_{\mathbf{W}} \mathcal{L}_{train}(\mathbf{W}, \alpha)$$

Survey

Automated Machine Learning on Graphs: A Survey

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Method	Micro		earch sp o Poolii		Layers		asks e Graph	Search Strategy	Performance Estimation	Other Characteristics
GraphNAS [34]	1	1	X	X	Fixed	1	X	RNN controller + RL	-	-
AGNN [43]	1	X	X	X	Fixed	1	X	Self-designed controller + RL	Inherit weights	-
SNAG [44]	1	1	X	X	Fixed	1	X	RNN controller + RL	Inherit weights	Simplify the micro search space
PDNAS [45]	1	1	X	×	Fixed	1	X	Differentiable	Single-path one-shot	-
POSE [46]	1	1	X	×	Fixed	1	X	Differentiable	Single-path one-shot	Support heterogenous graphs
NAS-GNN [47]	1	X	X	1	Fixed	1	X	Evolutionary algorithm		-
AutoGraph [48]	1	1	X	×	Various	1	X	Evolutionary algorithm	-	-
GeneticGNN [49]	1	X	X	1	Fixed	1	X	Evolutionary algorithm	-	-
EGAN [50]	1	1	X	X	Fixed	1	1	Differentiable	One-shot	Sample small graphs for efficiency
NAS-GCN [51]	1	1	1	X	Fixed	×	1	Evolutionary algorithm	-	Handle edge features
LPGNAS [52]	1	1	X	X	Fixed	1	X	Differentiable	Single-path one-shot	Search for quantisation options
You et al. [53]	1	1	X	1	Various	1	1	Random search	-	Transfer across datasets and tasks
SAGS [54]	1	X	X	X	Fixed	1	1	Self-designed algorithm	-	-
Peng et al. [55]	1	X	X	×	Fixed	X	1	CEM-RL [56]	-	Search spatial-temporal modules
GNAS[57]	1	1	X	X	Various	1	/	Differentiable	One-shot	
AutoSTG[58]	X	1	X	X	Fixed	1	X	Differentiable	One-shot+meta learning	Search spatial-temporal modules
DSS[59]	1	1	X	×	Fixed	1	X	Differentiable	One-shot	Dynamically update search space
SANE[60]	1	1	X	X	Fixed	1	X	Differentiable	One-shot	-
AutoAttend[61]	1	1	X	X	Fixed	1	1	Evolutionary algorithm	One-shot	Cross-layer attention

Table 1: A summary of different NAS methods for graph machine learnings.

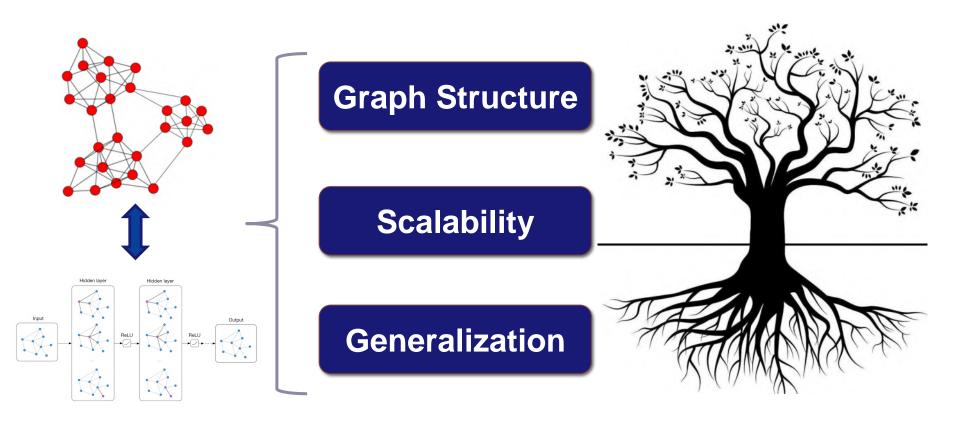
Paper collection: https://github.com/THUMNLab/awesome-auto-graph-learning
Tutorial KDD 2021: https://zw-zhang.github.io/files/2021_KDD_AutoMLonGraph.pdf

Automated Machine Learning on Graphs: A Survey. IJCAI, 2021.

Challenges for the Existing Methods

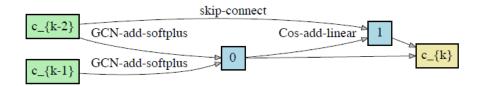
■ The existing methods partially solve the applicability problem

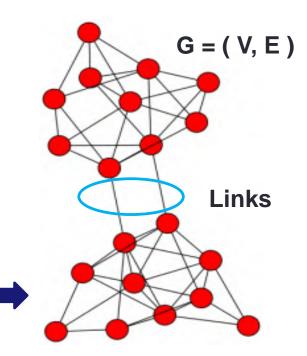
...but GraphNAS has many unique and unsolved challenges



Challenges: Graph Structure

- Graph structure is the key to GraphNAS
- Previous works assume fixed structures
- → Is the input graph structure optimal?
- → How to select architectures and graph structures that suit each other?





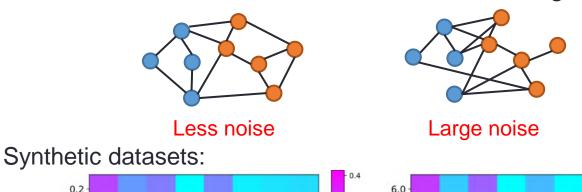
Challenge: how to theoretically model graph structure in GraphNAS

Analysis

Different operations fit graphs with different amount of information

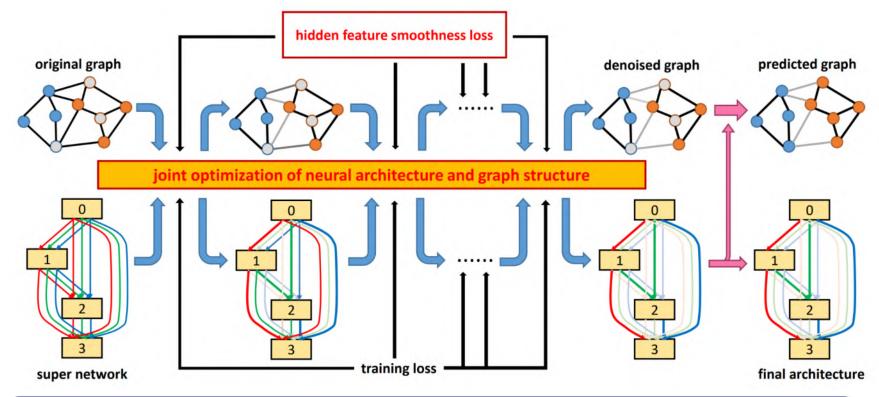
Theorem 2 Under our synthetic graph setting, let n be the number of edges connected the target node, the relative distance between the centers of two classes is |D|, which follows $D \sim \mathcal{N}(0, \beta^2)$. Then, the probability of that linear operation gives more accurate prediction than GCN on the target node is $P = \Phi\left[\frac{\sqrt{2n|D|}}{(\delta+1)\sqrt{(n+1)(n+2)}}\right]$.

■ Factors to determine the amount of information: signal to noise ratio



How to reduce structural noises while searching architectures?

GASSO: Jointly Learn Graph Structure and Neural Architecture



Learn graph structure and neural architecture through a joint optimization scheme

Graph Differentiable Architecture Search with Structure Learning. NeurIPS, 2021.

GASSO: Model

□ Formulation: tri-level optimization

$$\min_{\mathcal{A}} \mathcal{L}_{val}(W^*, \mathcal{A}, G^*)$$
s.t.
$$G^* = argmin_G \mathcal{L}_s(W^*, \mathcal{A}, G).$$

$$W^* = argmin_W \mathbb{E}_{\mathcal{A} \in \Gamma(\mathcal{A})} \mathcal{L}_{train}(W, \mathcal{A}, G).$$

■ Feature Smoothness Constraint

$$\mathcal{L}_{s} = \lambda \sum_{i,j}^{N} G_{ij} \| \mathbf{h}_{i} - \mathbf{h}_{j} \|_{2} + \sum_{i,j}^{N} (G_{ij} - G_{o,ij})^{2},$$

- Mask original edges: $G = G_o \odot M$
- Possible extensions: adding edges
 - □ Challenge: time complexity, there are $O(n^2)$ possible edges

GASSO: Experiments

■ Experiments on graph benchmarks

Dataset	Cora	Citeseer	Pubmed
GCN [†]	87.40	79.20	88.40
GAT^\dagger	87.26 ± 0.08	77.82 ± 0.11	86.83 ± 0.11
$ARMA^\dagger$	86.06 ± 0.05	76.50 ± 0.00	88.70 ± 0.24
DropEdge [†]	87.60 ± 0.05	78.57 ± 0.00	87.34 ± 0.24
DARTS	86.18 ± 0.36	74.96 ± 0.10	88.38 ± 0.18
GDAS	85.48 ± 0.30	74.20 ± 0.11	89.50 ± 0.14
ASAP	85.21 ± 0.13	75.14 ± 0.09	88.65 ± 0.10
XNAS	86.80 ± 0.14	76.33 ± 0.09	88.61 ± 0.25
GraphNAS [‡]	86.83 ± 0.56	79.05 ± 0.28	89.99 ± 0.43
GASSO	87.63 ± 0.29	79.61 ± 0.32	90.52 ± 0.24

■ Experiments on larger graph datasets

Dataset	Physics	CoraFull	ogbn-arxiv
GCN GAT	95.94 95.86	68.08 65.78	70.39 68.53
DARTS	95.74	68.51	69.52
GASSO	96.38	68.89	70.52

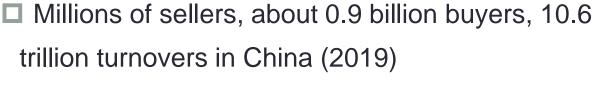
Challenge: Large-scale Graphs



Social Networks

- WeChat: 1.29 billion monthly active users (Aug 2022)
- Facebook: 2.8 billion active users (2020)

E-commerce Networks





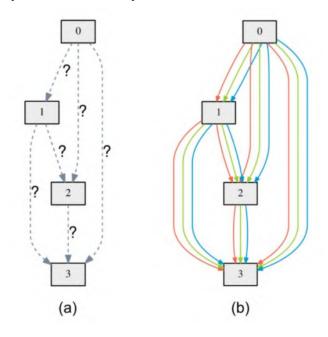
Citation Networks

■ 131 million authors, 185 million publications, 754 million citations (Aminer, Aug 2022)

Challenge: how to efficiently scale to billion-scale graphs

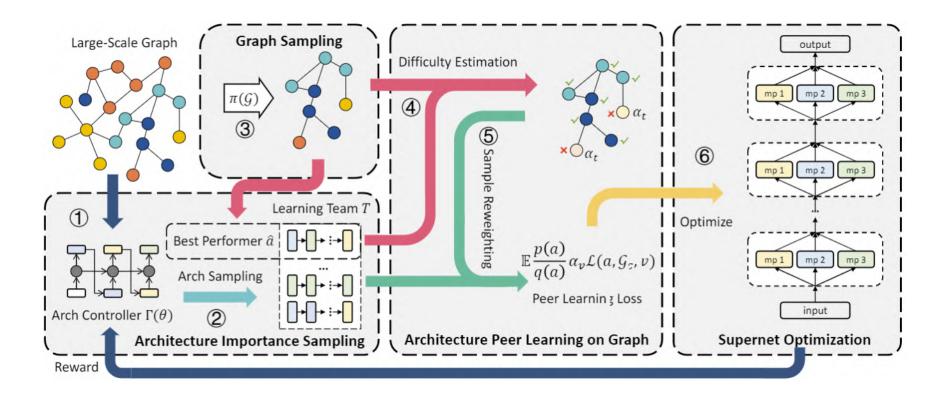
SuperNet Training

Supernet: combine all possible operations of the search space



- □ Trained by sampling architectures and back-propagations
- Supernet training for large-scale graphs:
 - Using the whole graph → computational bottleneck
 - □ Straight-forwardly sampling subgraphs → consistency issue

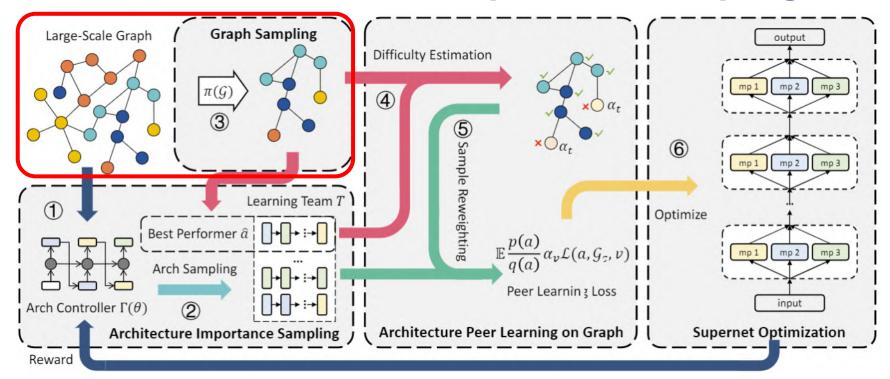
GAUSS: Large-scale Graph Neural Architecture Search



Jointly sample subgraphs and architectures to find the most suitable architecture

Large-scale Graph Neural Architecture Search. ICML, 2022.

GAUSS: Architecture Importance Sampling



- □ Goal: stabilize the training of the supernet
- Method: important sampling of architectures
 - \square $\Gamma(\mathcal{A})$: proposal distribution
 - Learning proposal distribution: reinforcement learning with GRU controller

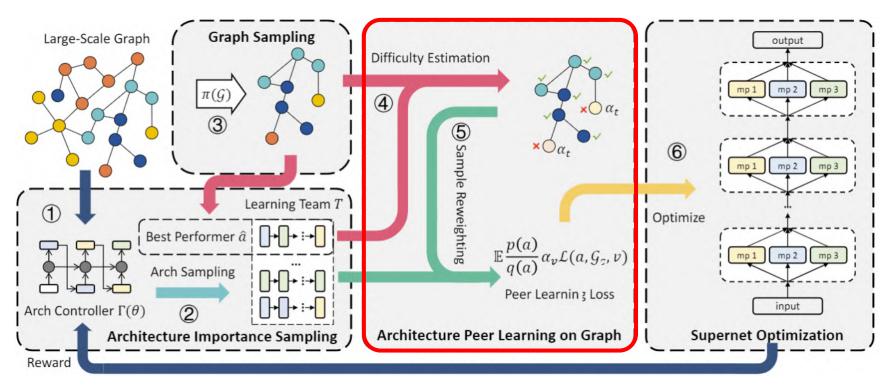
$$\begin{split} \mathbf{h}_0 &= \mathbf{0}, \; x_0 = <& \mathsf{bos}> \\ \mathbf{h}_l &= \mathsf{GRU}(\mathsf{Emb}(x_{l-1}), \mathbf{h}_{l-1}) \quad l \in \{1, ..., L\} \\ q(x_l|x_{0:l-1}) &= \mathsf{Softmax}(\mathbf{W}\mathbf{h}_l) \qquad l \in \{1, ..., L\} \\ x_l &= \mathsf{Sample}(q(x_l|x_{0:l-1})) \quad l \in \{1, ..., L\} \end{split}$$

$$\operatorname{Acc}(\mathcal{A}) \triangleq \mathbb{E}_{a \in \mathcal{A}} \operatorname{Acc}_{\mathrm{valid}}(a)$$
$$= \mathbb{E}_{a \sim \Gamma(\mathcal{A})} \frac{p(a)}{q(a)} \operatorname{Acc}_{\mathrm{valid}}(a),$$

Reward function: performance + regularizer

$$\theta = \operatorname{argmax}_{\theta}(\mathcal{R}(\theta) + \beta \mathcal{H}(\Gamma(\theta))),$$

GAUSS: Architecture Peer Learning on Graph



- □ Goal: smooth the optimization objective
- Assumption: "senior students" can teach "junior students"
- Method: assign weights to different samples, gradually progress from easier parts to difficult parts

$$\hat{\mathcal{L}} = \mathbb{E}_{T \in \mathcal{A}^n, \mathcal{G}_s \sim \pi(\mathcal{G})} \mathbb{E}_{a \in T, v \in \mathcal{V}_s} \alpha_v \mathcal{L}(a, \mathcal{G}_s, v)$$

$$\hat{a} = \underset{a \in T}{\operatorname{argmax}}_{a \in T} \mathbb{Acc}_{\operatorname{train}}(a, \mathcal{G}_s)$$

$$\alpha_v = \begin{cases} \alpha_t & l(\hat{a}, v) \neq y_v \text{ and } p(\hat{a}, v) > \lambda \\ 1 & \operatorname{Otherwise} \end{cases},$$

$$\alpha_t = \alpha_{min} \times (1 - \frac{t}{T_{total}}) + \frac{t}{T_{total}},$$

GAUSS: Experiments

DATASET	#Nodes	#Edges	
CS	18,333	81,894	
PHYSICS	34,493	247,962	
ARXIV	169,343	1,166,243	ŀ
PRODUCTS	2,449,029	61,859,140	
Papers 100M	111,059,956	1,615,685,872	4

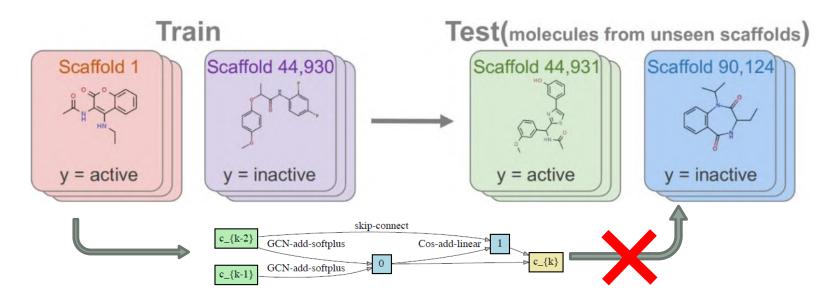
)x1000

Table 2. The results of our proposed method and baseline methods. We report both the validation and test accuracy [%] over 10 runs with different seeds. OOT means out-of-time (cannot converge within 1 single GPU day), while OOM means out-of-memory (cannot run on a Tesla V100 GPU with 32GB memory). The results of the best hand-crafted and automated method are in bold, respectively.

Methods	CS		Physics		Arxiv		Products		Papers100M	
	valid	test	valid	test	valid	test	valid	test	valid	test
GCN	94.10 _{0.21}	93.98 _{0.21}	96.29 _{0.05}	96.38 _{0.07}	72.76 _{0.15}	71.70 _{0.18}	91.75 _{0.04}	80.19 _{0.46}	70.32 _{0.11}	67.06 _{0.17}
GAT	$93.74_{0.27}$	$93.48_{0.36}$	$96.25_{0.23}$	$96.37_{0.23}$	$73.19_{0.12}$	$71.85_{0.21}$	$90.75_{0.16}$	$80.59_{0.40}$	$70.26_{0.16}$	$67.26_{0.06}$
SAGE	$95.65_{0.07}$	$95.33_{0.11}$	$96.76_{0.10}$	$96.72_{0.07}$	$73.11_{0.08}$	$71.78_{0.15}$	$91.75_{0.04}$	$80.19_{0.46}$	$70.32_{0.11}$	$67.06_{0.17}$
GIN	$92.00_{0.43}$	92.14 _{0.34}	96.03 _{0.11}	96.04 _{0.15}	71.16 _{0.10}	$70.01_{0.33}$	91.58 _{0.10}	$79.07_{0.52}$	68.98 _{0.16}	65.78 _{0.09}
GraphNAS	94.90 _{0.14}	94.67 _{0.23}	96.76 _{0.10}	96.72 _{0.07}	72.76 _{0.15}	71.70 _{0.18}	OOT	OOT	OOT	OOT
SGAS	$95.62_{0.06}$	$95.44_{0.06}$	$96.44_{0.10}$	$96.50_{0.11}$	$72.38_{0.11}$	$71.34_{0.25}$	OOM	OOM	OOM	OOM
DARTS	$95.62_{0.06}$	$95.44_{0.06}$	$96.21_{0.16}$	$96.40_{0.21}$	$73.43_{0.07}$	$72.10_{0.25}$	OOM	OOM	OOM	OOM
EGAN	$95.60_{0.10}$	$95.43_{\scriptstyle 0.05}$	$96.39_{0.18}$	$96.45_{0.19}$	$72.91_{\scriptstyle 0.25}$	$71.75_{0.35}$	OOM	OOM	OOM	OOM
Basic	95.13 _{0.07}	95.45 _{0.05}	96.25 _{0.06}	96.53 _{0.09}	73.28 _{0.08}	72.06 _{0.33}	91.79 _{0.11}	80.56 _{0.39}	69.49 _{0.37}	66.24 _{0.46}
GAUSS	96.08 _{0.11}	96.49 _{0.11}	96.79 _{0.06}	96.76 _{0.08}	73.63 _{0.10}	72.3 5 _{0.21}	$91.60_{0.12}$	81.26 _{0.36}	70.5 7 _{0.07}	67.32 _{0.18}

Challenge: Distribution Shifts

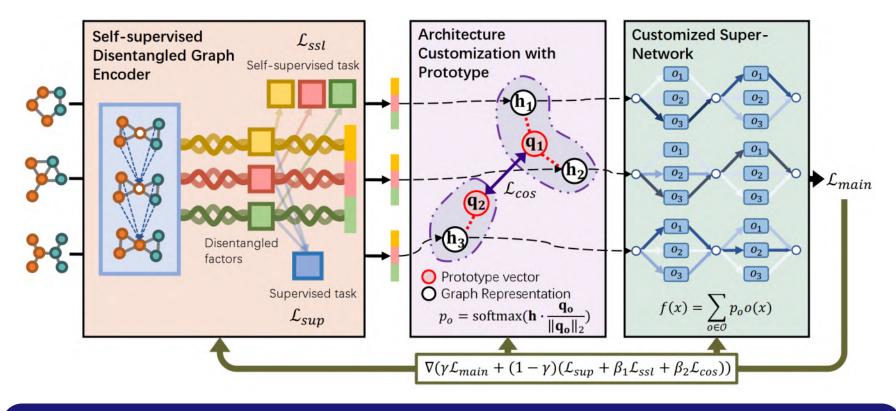
Distribution shifts naturally exist in graph data



■ Searching a fixed architecture on the training data may fail to generalize

Challenge: how to make GraphNAS capable of out-of-distribution generalization

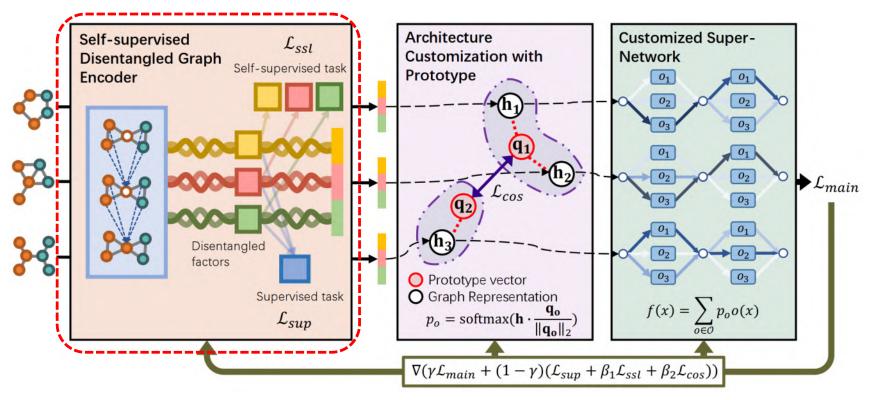
GRACES: Graph Neural Architecture Search under Distribution Shifts



Customize a unique GNN architecture for each graph instance to handle distribution shifts

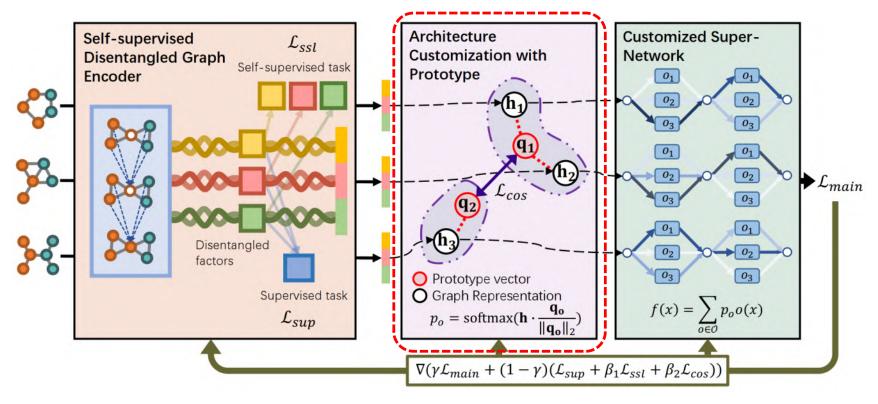
Graph Neural Architecture Search under Distribution Shifts. ICML, 2022.

GRACES: Graph Encoder



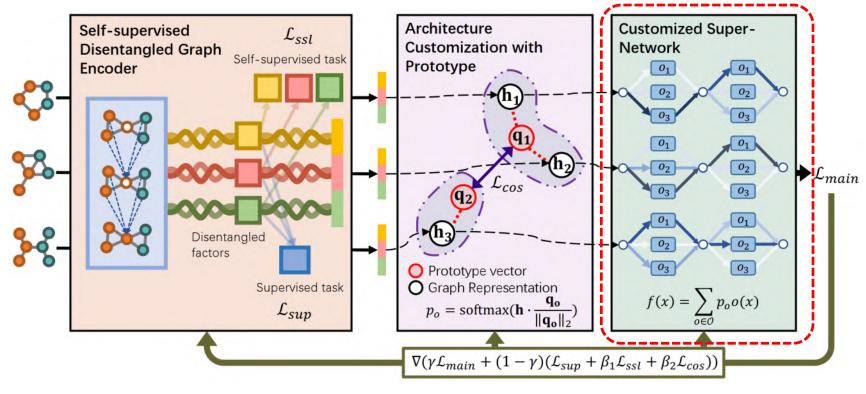
- □ Goal: learn a vector representation for each graph to reflect its characteristics
- Challenge: preserve diverse properties of the original graph
- Method: self-supervised disentangled graph encoder
 - Encoder: disentangled GNN $\mathbf{H}^{(l)} = \prod_{k=1}^{K} \text{GNN}(\mathbf{H}_{k}^{(l-1)}, \mathbf{A}) \quad \mathcal{L}_{sup} = \sum_{i=1}^{N_{tr}} \ell\left(\mathcal{C}\left(\mathbf{h}_{i}\right), y_{i}\right)$
 - Supervised loss: the downstream task
 - Self-supervised loss: node degree as regularization $\mathcal{L}_{ssl} = \sum_{i=1}^{n} \sum_{k=1}^{n} \ell_{ssl} \left(\hat{y}_{i,k}^{ssl}, y_{i,k}^{ssl} \right)$

GRACES: Architecture Customization



- Goal: customize an architecture based on the graph representation
- □ Assumption: graphs with similar characteristics need similar architectures
- Method: prototype based architecture customization
 - Probabilities of choosing operations: $\hat{p}_o^i = \mathbf{h} \cdot \frac{\mathbf{q}_o^i}{\|\mathbf{q}_o^i\|_2}, p_o^i = \frac{\exp\left(\hat{p}_o^i\right)}{\sum_{o' \in \mathcal{O}} \exp\left(\hat{p}_{o'}^i\right)},$
 - Regularizer to avoid mode collapse: $\mathcal{L}_{cos} = \sum_{i=o,o' \in \mathcal{O},o \neq o'} \frac{\mathbf{q}_o^i \cdot \mathbf{q}_{o'}^i}{\|\mathbf{q}_o^i\|_2 \|\mathbf{q}_o^i\|_2}$

GRACES: Learning Architecture Parameters



- □ Goal: learn parameters for the customized architectures
- Method: customized super-network $f^i(\mathbf{x}) = \sum_{co} p_o^i o(\mathbf{x})$
- Loss functions:

$$\mathcal{L} = \gamma \mathcal{L}_{main} + (1 - \gamma) \mathcal{L}_{reg}$$
$$\mathcal{L}_{reg} = \mathcal{L}_{sup} + \beta_1 \mathcal{L}_{ssl} + \beta_2 \mathcal{L}_{cos}$$

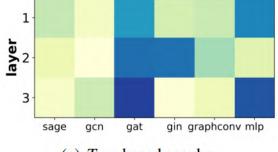
GRACES: Experiments

Synthetic OOD graph datasets

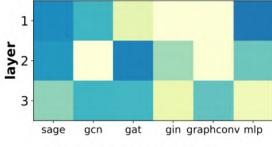
bias	b = 0.7	b = 0.8	b = 0.9
GCN	$48.39_{\pm 1.69}$	$41.55_{\pm 3.88}$	$39.13_{\pm 1.76}$
GAT	$50.75_{\pm 4.89}$	$42.48_{\pm 2.46}$	$40.10_{\pm 5.19}$
GIN	$36.83_{\pm 5.49}$	$34.83_{\pm 3.10}$	$37.45_{\pm 3.59}$
SAGE	$46.66_{\pm 2.51}$	$44.50_{\pm 5.79}$	$44.79_{\pm 4.83}$
GraphConv	$47.29_{\pm 1.95}$	$44.67_{\pm 5.88}$	$44.82_{\pm 4.84}$
MLP	$48.27_{\pm 1.27}$	$46.73_{\pm 3.48}$	$46.41_{\pm 2.34}$
ASAP	$54.07_{\pm 13.85}$	$48.32_{\pm 12.72}$	$43.52_{\pm 8.41}$
DIR	$50.08_{\pm 3.46}$	$48.22_{\pm 6.27}$	$43.11_{\pm 5.43}$
random	$45.92_{\pm 4.29}$	$51.72_{\pm 5.38}$	$45.89_{\pm 5.09}$
DARTS	$50.63_{\pm 8.90}$	$45.41_{\pm 7.71}$	$44.44_{\pm 4.42}$
GNAS	$55.18_{\pm 18.62}$	$51.64_{\pm 19.22}$	$37.56_{\pm 5.43}$
PAS	$52.15_{\pm 4.35}$	$43.12_{\pm 5.95}$	$39.84_{\pm 1.67}$
GRACES	$65.72_{\pm 17.47}$	$59.57_{\pm 17.37}$	$50.94_{\pm 8.14}$

Real-world OOD graph datasets

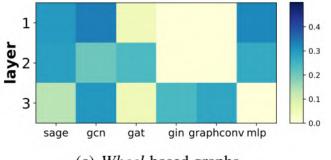
dataset	hiv	sider	bace
GCN	$75.99_{\pm 1.19}$	$59.84_{\pm 1.54}$	$68.93_{\pm 6.95}$
GAT	$76.80_{\pm 0.58}$	$57.40_{\pm 2.01}$	$75.34_{\pm 2.36}$
GIN	$77.07_{\pm 1.49}$	$57.57_{\pm 1.56}$	$73.46_{\pm 5.24}$
SAGE	$75.58_{\pm 1.40}$	$56.36_{\pm 1.32}$	74.85 ± 2.74
GraphConv	$74.46_{\pm 0.86}$	$56.09_{\pm 1.06}$	$78.87_{\pm 1.74}$
MLP	$70.88_{\pm0.83}$	$58.16_{\pm 1.41}$	$71.60_{\pm 2.30}$
ASAP	$73.81_{\pm 1.17}$	$55.77_{\pm 1.18}$	71.55 ± 2.74
DIR	$77.05_{\pm 0.57}$	$57.34_{\pm0.36}$	$76.03_{\pm 2.20}$
DARTS	$74.04_{\pm 1.75}$	$60.64_{\pm 1.37}$	$76.71_{\pm 1.83}$
PAS	$71.19_{\pm 2.28}$	$59.31_{\pm 1.48}$	$76.59_{\pm 1.87}$
GRACES	$77.31_{\pm 1.00}$	$61.85_{\pm 2.56}$	$79.46_{\pm 3.04}$







(b) Ladder-based graphs



(c) Wheel-based graphs

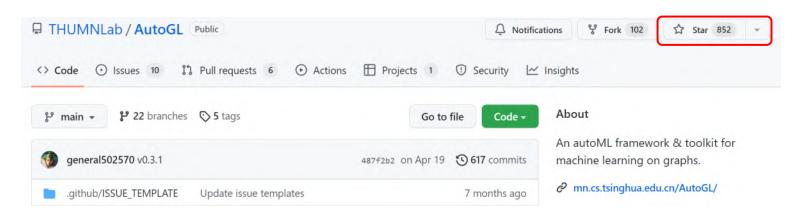
Customization of architectures

Introduction – AutoGL

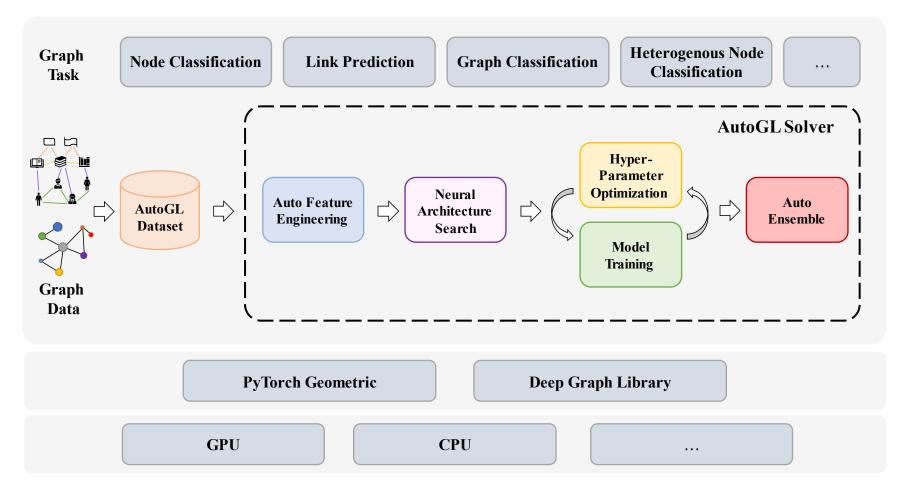
■ We design an autoML framework & toolkit for machine learning on graphs.



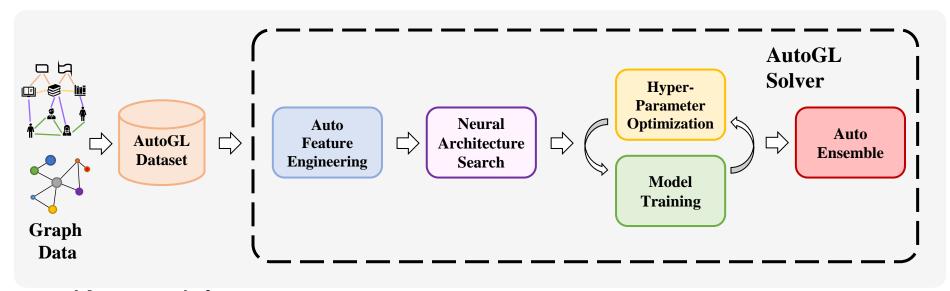
https://mn.cs.tsinghua.edu.cn/AutoGL https://github.com/THUMNLab/AutoGL



Overall Framework

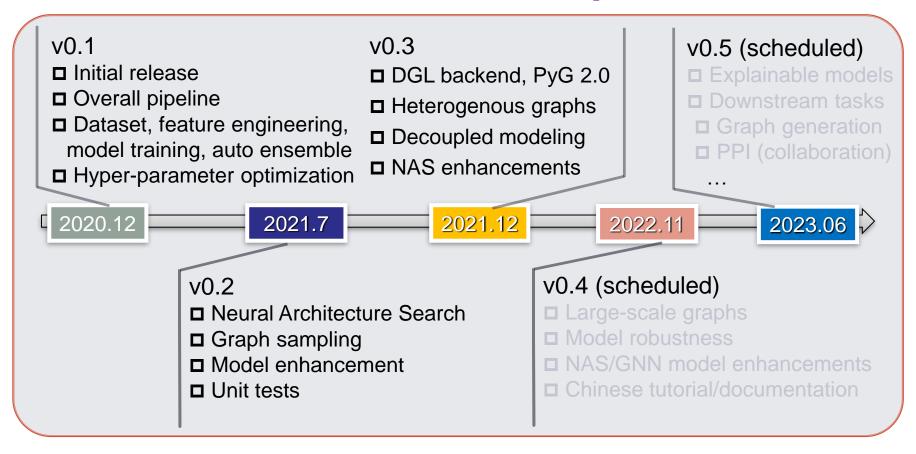


Modular Design



- □ Key modules:
 - AutoGL Dataset: manage graph datasets
 - AutoGL Solver: a high-level API to control the overall pipeline
 - ☐ Five functional modules:
 - Auto Feature Engineering
 - Neural Architecture Search
 - Hyper-parameter Optimization
 - Model Training
 - □ Auto Ensemble

AutoGL Roadmap



- □ Team member (~15)
 - □ Architect: Chaoyu Guan (v0.1-v0.3), Yijian Qin (v0.4-v0.5)
 - □ Programmer: Haoyang Li, Zeyang Zhang, Heng Chang, Zixin Sun, Beini Xie, Jie Cai, Zizhao Zhang, Jiyan Jiang, Yao Yang, Fang Shen
 - □ Tester: Yipeng Zhang, Peiwen Li

Media Coverage



Meet AutoGL: The First Ever AutoML Framework for Graph Datasets

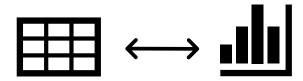
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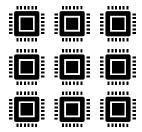


The Evaluation of Graph NAS Methods

- How to properly evaluate different GraphNAS algorithms
 - Incomparable and irreproducible results



Computationally expensive



■ Diverse evaluation protocols



NAS-Bench-Graph

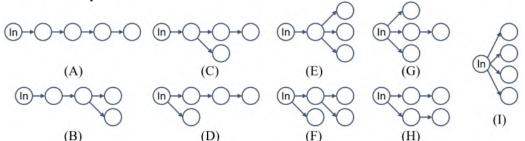
- The first tabular NAS benchmark for GraphNAS
 - □ Unified, Reproducible, Efficient
 - □ Provide detailed metrics of all architectures (exhaust 8,000 GPU hours)

Benchmark	Type	Search Space	Data	Datasets
NAS-Bench-101 [17]	Tabular	423k	CV	1
NAS-Bench-201 [4]	Tabular	6k	CV	3
NAS-Bench-1shot1 [19]	Tabular	364k	CV	1
NAS-Bench-ASR [12]	Tabular	8k	Acoustics	1
NAS-Bench-NLP [9]	Tabular	14k	NLP	2
HW-NAS-Bench [10]	Tabular	6k	CV	3
NATS-Bench [3]	Tabular	32k	CV	3
NAs-HPO-Bench-II [7]	Surrogate	192k	CV	1
NAS-Bench-MR [2]	Surrogate	10^{23}	CV	4
TransNAS-Bench [5]	Tabular	7k	CV	14
NAS-Bench-111 [16]	Surrogate	423k	CV	1
NAS-Bench-311 [16]	Surrogate	10^{18}	CV	1
NAS-Bench-Zero [1]	Tabular	34k	CV	3
Surr-NAS-Bench-FBNet [20]	Surrogate	10^{21}	CV	2
NAS-Bench-Graph	Tabular	26k	Graph	9

NAS-Bench-Graph: Benchmarking Graph Neural Architecture Search. NeurIPS, 2022.

NAS-Bench-Graph: Designs

- Search space:
 - Macro space:



26,206 architectures cover representative GNNs

- □ Operations: GCN, GAT, GraphSAGE, GIN, ARMA, k-GNN, MLP
- Datasets:

Dataset	#Vertices	#Links	#Features	#Classes	Metric
Cora	2,708	5,429	1,433	7	Accuracy
CiteSeer	3,327	4,732	3,703	6	Accuracy
PubMed	19,717	44,338	500	3	Accuracy
Coauthor-CS	18,333	81,894	6,805	15	Accuracy
Coauthor-Physics	34,493	247,962	8,415	5	Accuracy
Amazon-Photo	7,487	119,043	745	8	Accuracy
Amazon-Computers	13,381	245,778	767	10	Accuracy
ogbn-arxiv	169,343	1,166,243	128	40	Accuracy
ogbn-proteins	132,534	39,561,252	8	112	ROC-AUC

9 datasets different sizes/domains

NAS-Bench-Graph: Usage

■ Integrated with two representative libraries: AutoGL and NNI

Library	Method	Cora	CiteSeer	PubMed	CS	Physics	Photo	Computers	arXiv	proteins
AutoGL	GNAS Auto-GNN	82.04 _{0.17} 81.80 _{0.00}	0.20		0,00		0.00	84.74 _{0.20} 84.53 _{0.14}		
NNI	Random EA RL	82.09 _{0.08} 81.85 _{0.20} 82.27 _{0.21}	$70.48_{0.12}$	77.96 _{0.12}	$90.60_{0.07}$		92.430.02	84.78 _{0.14} 84.29 _{0.29} 84.90 _{0.19}	$71.91_{0.06}$	$77.93_{0.21}$
The	top 5%	80.63	69.07	76.60	90.01	91.67	91.57	82.77	71.69	78.37

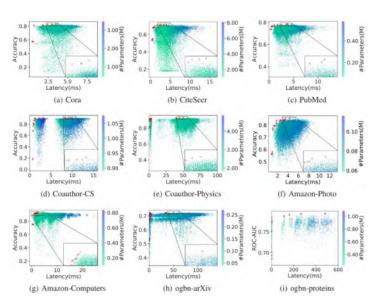
■ Example: ~10 lines of codes

```
from readbench import read
bench = read('cora0.bench') # dataset and seed
info = bench[arch.valid_hash()]
epoch = 50
info['dur'][epoch][0]
                        # training performance
                        # validation performance
info['dur'][epoch][1]
info['dur'][epoch][2]
                        # testing performance
info['dur'][epoch][3]
                        # training loss
info['dur'][epoch][4]
                        # validation loss
info['dur'][epoch][5] # testing loss
info['dur'][epoch][6]
                        # best performance
```

Open source: https://github.com/THUMNLab/NAS-Bench-Graph

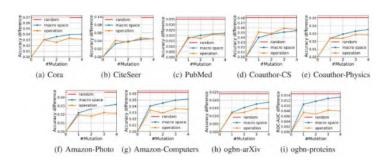
NAS-Bench-Graph: Benchmarking Graph Neural Architecture Search. NeurIPS, 2022.

NAS-Bench-Graph: Analysis

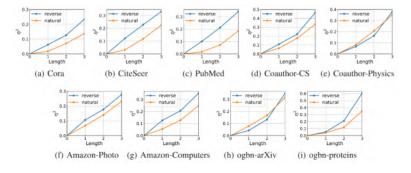


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Performance distribution



Architecture distribution & Correlation

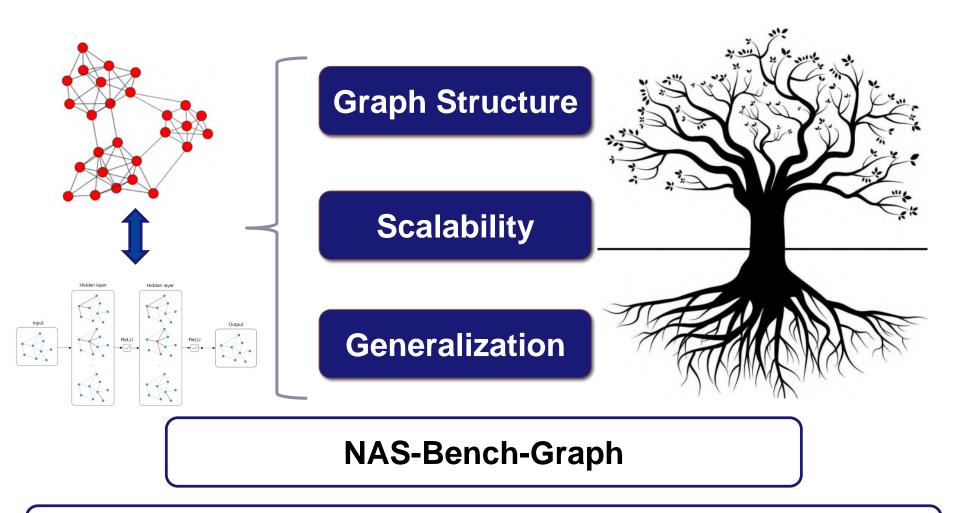


Architecture space smoothness

Influence of operations at different depth

NAS-Bench-Graph: Benchmarking Graph Neural Architecture Search. NeurIPS, 2022.

Recap: Our Recent Works on GraphNAS



AutoGL: a library for automated graph machine learning

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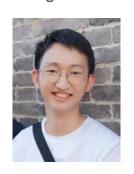
Yijian Qin Tsinghua Univ.



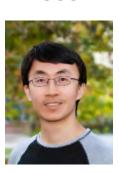
Xin Wang Tsinghua Univ.



Zeyang Zhang Tsinghua Univ.



Pengtao Xie UCSD



THANK YOU!

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